

Algorithm Design Techniques ***(II)***

Brute Force Algorithms.
Greedy Algorithms.
Backtracking

Brute Force Algorithms

- Distinguished not by their structure or form, but by the way in which the problem to be solved is approached
- They solve a problem in the most simple, direct or obvious way
 - Can end up doing far more work to solve a given problem than a more clever or sophisticated algorithm might do
 - Often easier to implement than a more sophisticated one and, because of this simplicity, sometimes it can be more efficient.

Example: Counting Change

- Problem: a cashier has at his/her disposal a collection of notes and coins of various denominations and is required to count out a specified sum using the smallest possible number of pieces
- Mathematical formulation:
 - Let there be n pieces of money (notes or coins),
 $P = \{p_1, p_2, \dots, p_n\}$
 - let d_i be the denomination of p_i
 - To count out a given sum of money A we find the smallest subset of P , say $S \subseteq P$, such that
$$\sum_{p_i \in S} d_i = A$$

Example: Counting Change (2)

- Can represent S with n variables $X = \{x_1, x_2, \dots, x_n\}$ such that

$$\begin{cases} x_i = 1 & p_i \in S \\ x_i = 0 & p_i \notin S \end{cases}$$

- Given $\{d_1, d_2, \dots, d_n\}$ our objective is:

$$\sum_{i=1}^n x_i$$

- Provided that:

$$\sum_{p_i \in S} d_i = A$$

Counting Change: Brute-Force Algorithm

- $\forall x_i \in X$ is either a 0 or a 1 $\Rightarrow 2^n$ possible values for X .
- A brute-force algorithm finds the best solution by enumerating all the possible values of X .

- For each possible value of X we check first if the constraint

$$\sum_{i=1}^n d_i x_i = A$$

is satisfied.

- A value which satisfies the constraint is called a feasible solution
- The solution to the problem is the feasible solution which minimizes

$$\sum_{i=1}^n x_i$$

which is called the objective function .

Counting Change: Brute-Force Algorithm (3)

- There are 2^n possible values for $X \Rightarrow$ running time of a brute-force solution is $\Omega(2^n)$
- The running time needed to determine whether a possible value is a feasible solution is $O(n)$, and
- The time required to evaluate the objective function is also $O(n)$.
- Therefore, the running time of the brute-force algorithm is $O(n2^n)$.

Applications of Greedy Strategy

- Optimal solutions:
 - Change making
 - Minimum Spanning Tree (MST)
 - Single-source shortest paths
 - Simple scheduling problems
 - Huffman codes
- Approximations:
 - Traveling Salesman Problem (TSP)
 - Knapsack problem
- Other combinatorial optimization

Counting Change: Greedy Algorithm

- A cashier does not really consider all the possible ways in which to count out a given sum of money.
- Instead, she/he counts out the required amount beginning with the largest denomination and proceeding to the smallest denomination
- Example: $\{d_1, d_2, \dots, d_{10}\} = \{1, 1, 1, 1, 1, 5, 5, 10, 25, 25\}$. Count 32: 25, 5, 1, 1
- Greedy strategy: once a coin has been counted out it is never taken back
- If the pieces of money (notes and coins) are sorted by their denomination, the running time for the greedy algorithm is $O(n)$.
- Greedy algorithm does not always produce the best solution. Example: set: $\{1, 1, 1, 1, 1, 10, 10, 15\}$. count 20: 15, 1, 1, 1, 1, 1. But best solution is: 20: 10, 10.

Example: 0/1 Knapsack Problem

- Given:
 - A set of n items from which we are to select some number of items to be carried in a knapsack.
 - Each item has both a *weight* and a *profit*.
 - The *objective*: chose the set of items that fits in the knapsack and maximizes the profit.
- Let:
 - w_i be the weight of item i ,
 - p_i be the profit accrued when item i is carried in the knapsack, and
 - W be the capacity of the knapsack.
 - x_i be a variable which has the value 1 when item i is carried in the knapsack, and 0 otherwise

Example: 0/1 Knapsack Problem (2)

- Given $\{w_1, w_2, \dots, w_n\}$ and $\{p_1, p_2, \dots, p_n\}$, our *objective* is to maximize

$$\sum_{i=1}^n p_i x_i$$

- subject to the constraint

$$\sum_{i=1}^n w_i x_i \leq W$$

- Can solve this problem by exhaustively enumerating the feasible solutions and selecting the one with the highest profit.
 - since there are 2^n possible solutions, the running time required for the brute-force solution becomes prohibitive as n gets large.

Example: 0/1 Knapsack Problem (3)

- **Possibilities** (provided the capacity of the knapsack is not exceeded):
- **Greedy by Profit**
 - At each step select from the remaining items the one with the highest profit.
 - Chooses the most profitable items first.
- **Greedy by Weight**
 - At each step select from the remaining items the one with the least weight.
 - Tries to maximize the profit by putting as many items into the knapsack as possible.
- **Greedy by Profit Density**
 - At each step select from the remaining items the one with the largest *profit density*, p_i / w_i .
 - Tries to maximize the profit by choosing items with the largest profit per unit of weight.

Example: 0/1 Knapsack Problem (4)

- Assume $W = 100$

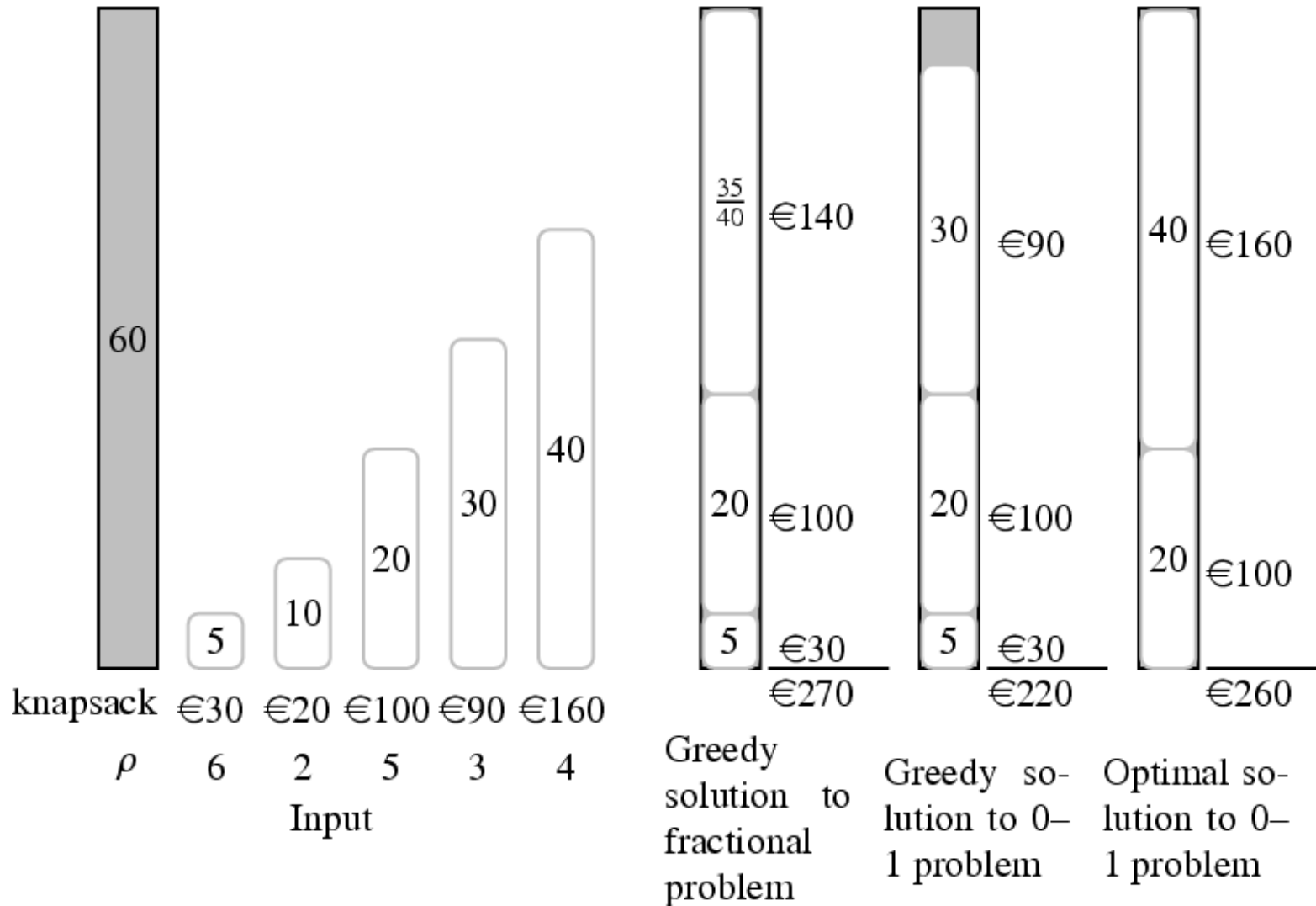
				greedy by			
i	w_i	p_i	p_i/w_i	profit	weight	density	optimal solution
1	100	40	0.4	yes	no	no	no
2	50	35	0.7	no	no	yes	yes
3	45	18	0.4	no	yes	no	yes
4	20	4	0.2	no	yes	yes	no
5	10	10	1.0	no	yes	yes	no
6	5	2	0.4	no	yes	yes	yes
total weight				100	80	85	100
total profit				40	34	51	55

- Note: solution not always optimal

Fractionary Knapsack Problem

- Thief robbing a store; finds n items which can be taken.
- Item i is worth $\text{€ } v_i$ and weighs w_i pounds ($v_i, w_i \in \mathbf{N}$)
- Thief wants to take as valuable a load as possible, but has a knapsack that can only carry W total pounds
- 0–1 knapsack problem: each item must be left (0) or taken (1) in its entirety
- Fractionary knapsack problem: thief is allowed to take any fraction of an item for a fraction of the weight and a fraction of the value. Greedy algorithm:
 - Let $\rho_i = v_i/w_i$ be the value per pound ratio (profit density)
 - Sort the items in decreasing order of ρ_i , and add them in this order

Knapsack Problem Example



An Activity-Selection Problem

- Let S be a set of activities $S = \{a_1, a_2, \dots, a_n\}$
 - They use resources, such as lecture hall, one lecture at a time
 - Each a_i , has a start time s_i , and finish time f_i , with $0 \leq s_i < f_i < \infty$.
 - a_i and a_j are compatible if $[s_i, f_i)$ and $[s_j, f_j)$ do not overlap
- Goal: select maximum-size subset of mutually compatible activities.

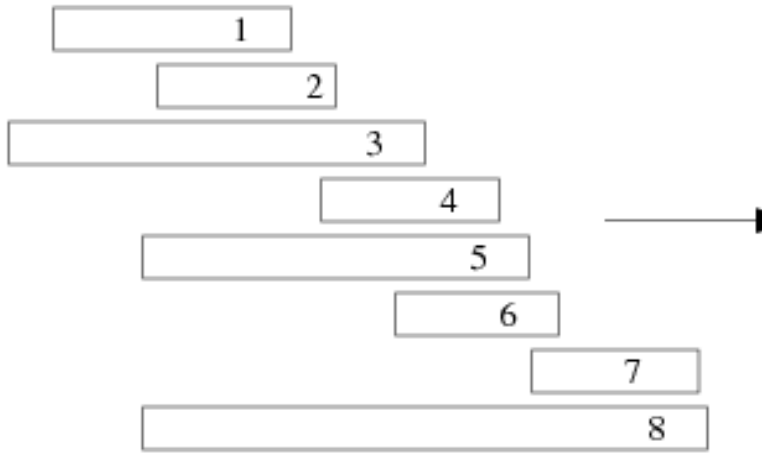
Greedy Activity Scheduler

GREEDYACTIVITYSCHEDULER(s, f)

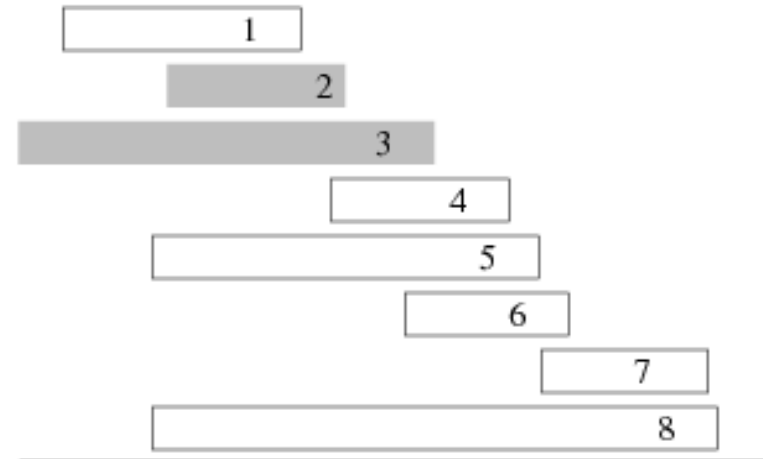
```
1   $n \leftarrow \text{length}[s]$            ▷ we assume  $f[1..n]$  is already sorted
2   $A \leftarrow \langle 1 \rangle$          ▷ schedule activity 1 first
3   $prev \leftarrow 1$ 
4  for  $i \leftarrow 2$  to  $n$ 
5      do if  $s_i \geq f_{prev}$        ▷ no interference?
6          then append  $i$  to  $A$ 
7               $prev \leftarrow i$    ▷ schedule  $i$  next
8  return  $A$ 
```


Greedy Activity Scheduling Example

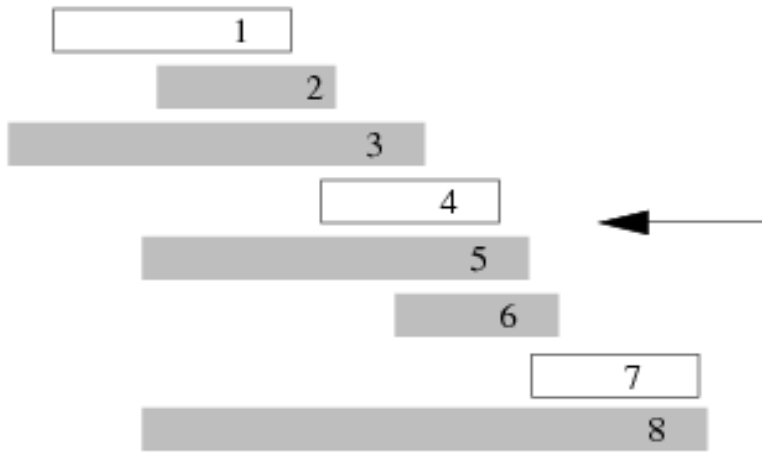
Input:



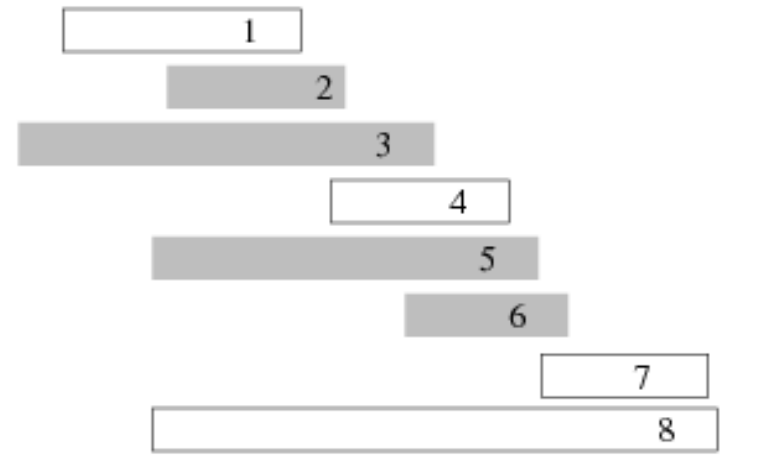
Add 1:



Add 7:



Add 4:



Prefix Codes

- A prefix code is a code in which no codeword is also a prefix of another codeword. For example, the variable-length $a=0$, $b=101$, $c=100$, $d=111$, $e=1101$, $f=1100$ code is a prefix code.
 - Variable-length prefix codes can be simply encoded and decoded.
- For example, the four characters *cabf* is encoded as:
10001011100
- For decoding it, we chose the prefix which forms a code, remove it, and continue with the rest.
 - Decoding a word can be understood as finding a leaf in a tree, starting from the root.

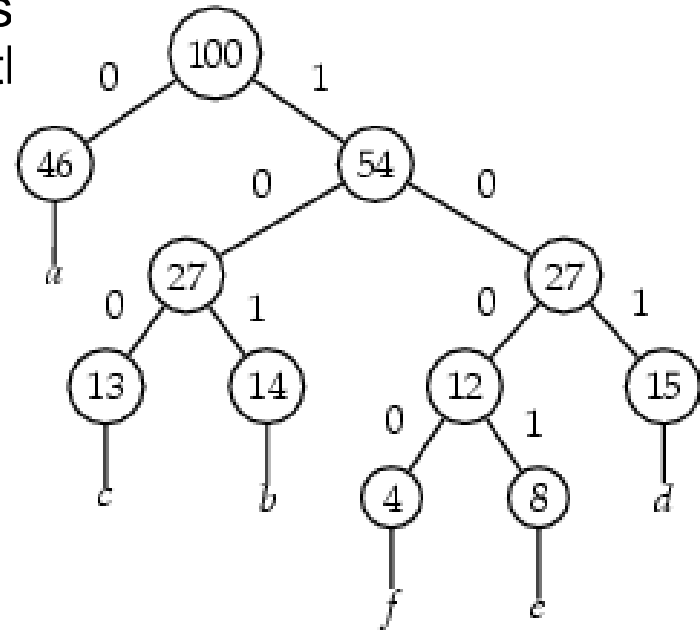
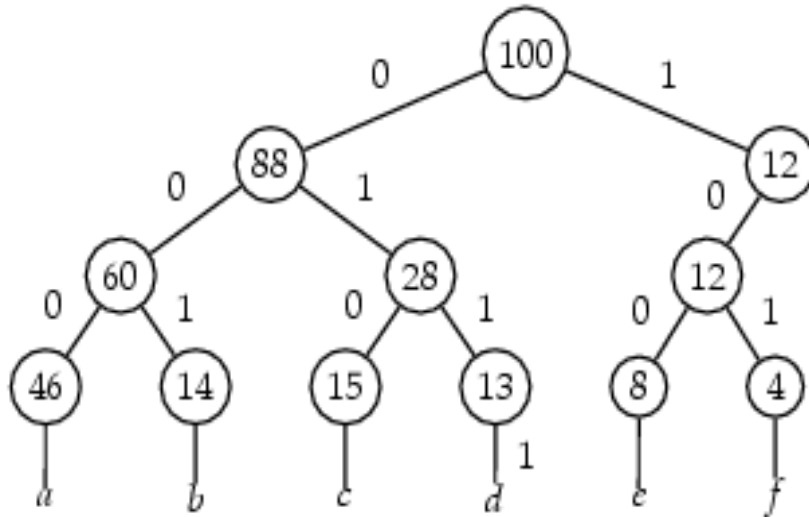
Huffman Codes

- Huffman codes are an - in a certain sense - optimal way for compressing data, typically for storage or transmission.
 - Suppose the input is a sequence of characters and suppose that – as is typically with text - certain characters appear more frequent than other characters.
 - The idea is that rather than using a fixed-length binary code for the text, using a variable-length code where more frequent characters have a shorter code than less frequent characters.
- Example:
 -
 - Frequency
 - Fixed-length code
 - Variable-length code
 - A file with 100 characters takes 300 bits with the fixed-length code and 224 bits with the variable-length code.

	a	b	c	d	e	f
Frequency	46	14	13	15	8	4
Fixed-length code	000	001	010	011	100	101
Variable-length code	0	101	100	111	1101	1100

Codes as Trees

- Trees corresponding to codes, with each node labeled by its frequency the leaves labeled with character coded by that path



- Assume that $f(z)$ is the frequency of z and $d_T(z)$ is the depth of z 's leaf in the tree, which is the same as the length of the codeword for z . The number of bits for encoding a file can be computed as follows

$$B(T) = \left(\sum_{z \in C} f(z) d_T(z) \right)$$

Greedy Algorithm for Huffman Codes

- A code with tree T is optimal if $B(T)$ is minimal (for a fixed frequency of the characters)
 - Huffman codes are optimal prefix codes. For example, the code to the right on the previous slide is a Huffman code.
 - A greedy algorithm for constructing Huffman codes is based on following two properties:
 - If x and y are two characters with lowest frequency, then there exists an optimal prefix code in which the codes of x and y differ only in their last bit (hence have same length)
 - If T is an optimal prefix code for alphabet C and $x, y \in T$ are two leaves, then replacing x, y with a new parent z with $f(z)=f(x)+f(y)$ results in an optimal prefix code for $C - \{x, y\} \cup \{z\}$.

Constructing Huffman Codes

- Huffman's algorithm uses a priority queue Q to identify the two least-frequent objects to merge together.

HUFFMAN(C)

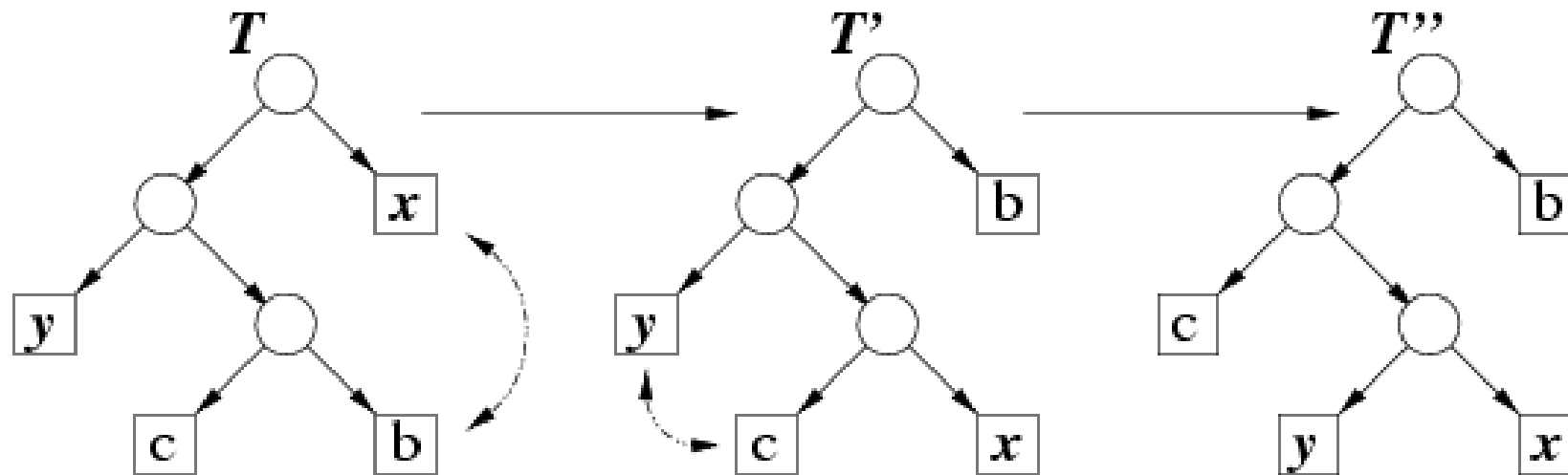
```
1   $n \leftarrow |C|$ 
2   $Q \leftarrow C$ 
3  for  $i \leftarrow 1$  to  $n - 1$ 
4      do  $z \leftarrow \text{ALLOCATENODE}()$ 
5           $x \leftarrow \text{left}[z] \leftarrow \text{EXTRACTMIN}(Q)$ 
6           $y \leftarrow \text{right}[z] \leftarrow \text{EXTRACTMIN}(Q)$ 
7           $f[z] = f[x] + f[y]$ 
8           $\text{INSERT}(Q, z)$ 
9  return  $\text{EXTRACTMIN}(Q)$ 
```

- The algorithm returns the single element left in the heap, which is the sum of all frequencies of all characters of C .

Huffman Correctness

- Let T be any optimal prefix code tree, and let b and c be two siblings at the maximum depth of the tree.
- Assume without loss of generality that $p(b) \leq p(c)$ and $p(x) \leq p(y)$
- since x and y have the two smallest probabilities it follows that $p(x) \leq p(b)$ and $p(y) \leq p(c)$
- b and c are at the deepest level: $d(b) \geq d(x)$ and $d(c) \geq d(y)$
- Thus, we have $p(b) - p(x) \geq 0$ and $d(b) - d(x) \geq 0$, and hence their product is nonnegative.
- Now switch the positions of x and b in the tree, resulting in a new tree T' .

Huffman Correctness (2)



$$\begin{aligned}
 B(T') &= B(T) - p(x)d(x) + p(x)d(b) - p(b)d(b) + p(b)d(x) \\
 &= B(T) + p(x)(d(b) - d(x)) - p(b)(d(b) - d(x)) \\
 &= B(T) - (p(b) - p(x))(d(b) - d(x)) \\
 &\leq B(T) \text{ because } (p(b) - p(x))(d(b) - d(x)) \geq 0.
 \end{aligned}$$

Huffman Correctness (2)

- Claim: Huffman's algorithm produces the optimal prefix code tree
- Proof (by induction on n)
 - Assume: $< n$ characters, Huffman's algorithm is guaranteed to produce the optimal tree (OPT).
 - Suppose we have exactly n characters. The previous claim states that we may assume that in OPT, the two characters of lowest probability x and y will be siblings at the lowest level of the tree.
 - Remove x and y , replacing them with a new character z whose probability is $p(z) = p(x) + p(y)$. Thus $n - 1$ characters remain.

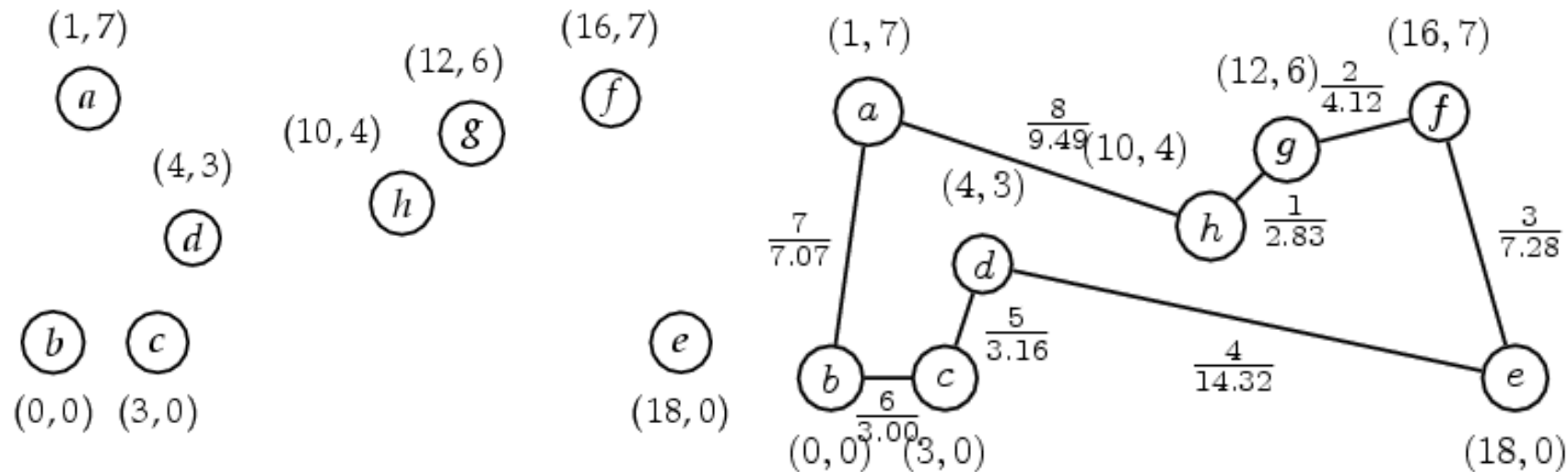
Huffman Correctness (3)

- Consider any prefix code tree T made with this new set of $n - 1$ characters
- We can convert it into a prefix code tree T' for the original set of characters by undoing the previous operation and replacing z with x and y (adding a "0" bit for x and a "1" bit for y). The cost of the new tree is

$$\begin{aligned} B(T') &= B(T) - p(z)d(z) + p(x)(d(z) + 1) + p(y)(d(z) + 1) \\ &= B(T) - (p(x) + p(y))d(z) + (p(x) + p(y))(d(z) + 1) \\ &= B(T) + (p(x) + p(y))(d(z) + 1 - d(z)) \\ &= B(T) + p(x) + p(y). \end{aligned}$$

The Traveling Salesman Problem (TSP)

- Tour (Hamilton) (Hamiltonian cycle)
 - Given a graph with weights on the edges a tour is a simple cycle that includes all the vertices of the graph.
- TSP
 - Given a graph with weights on the edges, find a tour having a minimum sum of edge weights.



Here weights are Euclidean distances

A Greedy Algorithm for TSP

- Based on Kruskal's algorithm. It only gives a suboptimal solution in general.
- Works for complete graphs. May not work for a graph that is not complete.
- As in Kruskal's algorithm, first sort the edges in the increasing order of weights.
- Starting with the least cost edge, look at the edges one by one and select an edge only if the edge, together with already selected edges,
 1. does not cause a vertex to have degree three or more
 2. does not form a cycle, unless the number of selected edges equals the number of vertices in the graph.

The n -Queens Problem

- The problem is to place n queens (chess pieces) on an n by n board so that no two queens are in the same row, column or diagonal

		Q	
Q			
			Q
	Q		

The 4 by 4 board above shows a solution for $n = 4$

- But first we will introduce an algorithm strategy called **backtracking**, which can be used to construct ***all*** solutions for a given n .

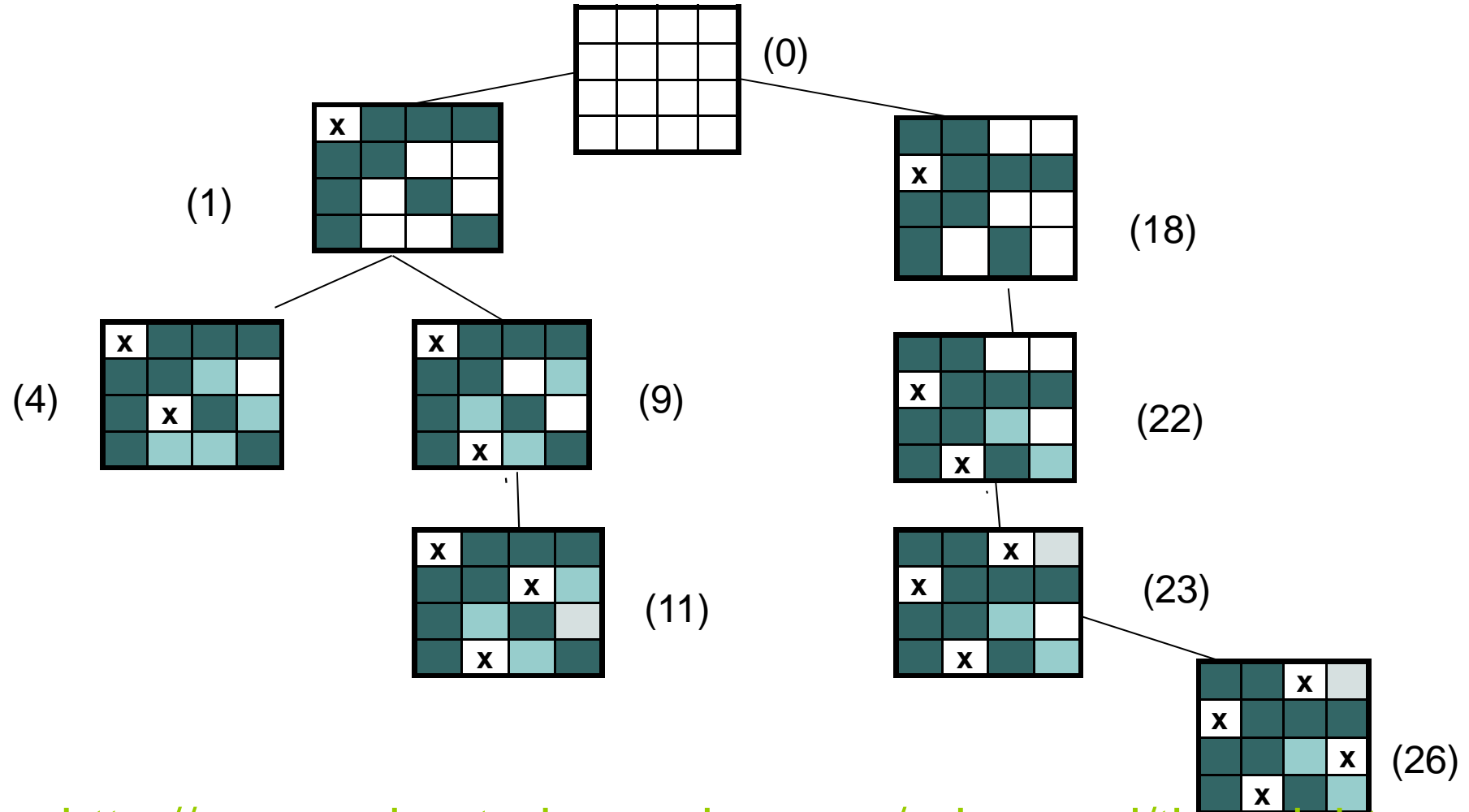
The n-Queens Problem

- We can solve this problem by generating a dynamic tree in a *depth-first* manner
 - Try to place a queen in each column from the first to the last
 - For each column, we must select a row
 - Start by placing a queen in row 1 of the first column
 - Then we check the rows in the second column for positions that do not conflict with our choice for the first column
 - After placing a queen in the second row, we continue to the third, etc.

The n-Queens Problem

- If at any point we find we cannot place a queen in the current column, we back up to the previous column and try a different row for that column
- We then continue trying to place more queens
- This process can be visualized by a tree of configurations
- The nodes are partial solutions of the problem
- The root is an empty board
- The children of the root will be boards with placements in the first column
- We will generate the nodes of the tree dynamically in a depth-first way

n-Queens Problem Instance



- http://www.animatedrecursion.com/advanced/the_eight_queens_problem.html

Backtracking Solution to n-Queens Problem

- We could continue with the previous example to obtain all possible solutions for $n = 4$
- Our goal now is to convert this approach into an explicit algorithm
- We track the position of the queens by using an array `row`
- `row[k]` is the row in column k containing a queen
- The key function is the recursive function `rnQueens`
- When `rnQueens(k, n)` is called, queens have been successfully placed in columns 1 to $k - 1$
- The function then attempts to place a queen in column k
- If it is successful, then
 - if $k = n$, it prints the solution
 - if $k < n$, it makes the call `rnQueens(k+1, n)`
 - if $k > n$ then returns to the call `rnQueens(k-1, n)`

Backtracking Solution to n-Queens Problem

- To test for a valid position for a queen in column k , we use a function *positionOK(k,n)* which returns true if and only if the queen tentatively placed in column k does not conflict with the queens in positions 1 to $k - 1$
- The queens in columns i and k conflict if
 - they are in the same row: $row[i] = row[k]$
 - or in the same diagonal: $|row[k] - row[i]| == k - i$
- We are thus led to our first version of the functions

Backtracking Solution to n-Queens Problem

nQueens(n)

```
{  
  rnQueens(1, n)  
}
```

positionOK(k)

```
{  
  for i = 1 to k-1  
    if (row[k] = row[i] ||  
        abs(row[k]-row[i]) = k-i)  
      return false;  
  return true;  
}
```

rnQueens(k,n) {

```
for row[k] = 1 to n
```

```
  if (positionOK(k) )
```

```
    if ( k = n )
```

```
      {
```

```
        for i = 1 to n
```

```
          print(row[i] + " ");
```

```
          println;
```

```
      }
```

```
    else
```

```
      rnQueens(k+1, n)
```

```
  }
```

http://www.animatedrecursion.com/advanced/the_eight_queens_problem.html

http://en.wikipedia.org/wiki/Eight_queens_puzzle

n-Queens Problem: Running Time

- Improvements can be made so that *positionOK(k,n)* runs in $O(1)$ time rather than $O(k)$ time.
- We will obtain an upper bound for the running time of our algorithm by bounding the number of times *rnQueens(k,n)* is called for each $k < n$
 - $k = 1$: 1 time, by *nQueens*
 - $1 < k < n$: $n(n-1)\dots(n-k+2)$ at most, since there are $n(n-1)\dots(n-k+2)$ ways to place queens in the first $k-1$ columns in distinct rows
- Ignoring recursive calls, *rnQueens(k,n)* executes in $\Theta(n)$ time for $k < n$.
- This gives a worst-case bound for *rnQueens(k,n)* of $n [n(n-1)\dots(n-k+2)]$ for $1 < k < n$
- For $k = n$, there is at most one placement possible for the queen. Also, the loop in *rnQueens(k,n)* executes in $\Theta(n)$ time.

n-Queens Problem: Running Time (2)

- There are $n(n-1)\dots 2$ ways for the queens to have been placed in the first $n-1$ columns, so the worst case time for $rnQueens(n, n)$ is

$$n(n-1)\dots 2$$

- Combining the previous bounds, we get the bound

$$\begin{aligned} & n [1 + n + n(n-1) + \dots + n(n-1) \dots 2] \\ & = n \cdot n! [1/n! + 1/(n-1)! + \dots + 1/1!] \end{aligned}$$

A result from calculus:

$$e = \sum_{i=0}^{\infty} \frac{1}{i!} = 1 + \sum_{i=1}^{\infty} \frac{1}{i!}$$

- This means that $n \cdot n! [1/n! + 1/(n-1)! + \dots + 1/1!] \leq n \cdot n! \cdot (e - 1)$
- We thus have that our algorithm runs in $O(n \cdot n!)$ time

General Form of a Backtracking Algorithm

- Solution is of the form $x[1], \dots, x[n]$, where the values of $x[i]$ are from some set S – this set would be $\{1, \dots, n\}$ for the n -queens problem
- General form:

// invocation

backtrack(n)

{

rbacktrack(1, n)

}

rbacktrack(k, n)

{

for each $x[k] \in S$

if (*bound(k)*)

if ($k = n$)

 {*//output a solution;*

//stop if one solution is desired

for $i = 1$ **to** n

 print($x[i]$ + “ ”)

 println()

 }

else

backtrack(k+1, n)

}

General Form of a Backtracking Algorithm

- The function $bound(k)$ assumes that $x[1], \dots, x[k-1]$ is a partial solution and that $x[k]$ has been given a value
- The key is to choose a bounding function that eliminates many potential nodes from the tree (idea of branch –and-bound)

Hamiltonian-Cycle Problem

- The problem of determining if a graph has a Hamiltonian cycle is known to be NP-complete
- This means it is extremely unlikely that there is a polynomial time algorithm for this problem
- We can use backtracking to get an algorithm for this problem with decent running time for moderate size graphs
- We number the vertices of the graph from **1** to n and use the adjacency matrix representation
- We want $x[1], \dots, x[n]$ to be vertices such that $x[1] \dots x[n] x[1]$ is a Hamiltonian cycle for the graph
- Thus they must be distinct and each vertex and its successor in the list must be adjacent
- Since a Hamiltonian cycle passes through every vertex, we may assume it starts at vertex **1**

Backtracking Algorithm for Hamiltonian Cycles

```
hamilton(adj, x) {  
    n = adj.last  
    x[1] = 1  
    used[1] = true  
    for i = 2 to n  
        used[i] = false  
        rhamilton(adj, 2, x)  
    }
```

```
pathOK(adj, k, x) {  
    n = adj.last  
    if ( used[x[k]] )  
        return false  
    if ( k < n )  
        return ( adj[ x[k-1], x[k] ] )  
    else  
        return ( adj[ x[k-1], x[k] ] ^ adj[ x[k], x[1] ] )  
}
```

```
rhamilton(adj, k, x) {  
    n = adj.last  
    for x[k] = 2 to n  
        if ( pathOK(adj, k, x) ) {  
            used[k] = true  
            if ( k = n )  
                return true  
            else if ( rhamilton(adj, k+1, x) )  
                return true  
        }  
    return false  
}
```

http://en.wikipedia.org/wiki/Knight's_tour

Reading

- AHU, chapter 10, sections 3, 4 and 5
- Preiss, chapter: Algorithmic Patterns and Problem Solvers, sections Brute-Force and Greedy Algorithms
- CLR, chapter 17, CLRS chapter 16
- Notes