

Pattern recognition systems – Lab 12

Support Vector Machine – Classification

1. Objectives

In this lab session we will implement the simple linear classifier described in the previous lab and we will study the mechanisms of support vector classification based on soft margin classifiers.

2. Theoretical Background

2.1. Hard-margin classifiers

In explaining the problem of hard and soft margin classifiers we will start from a simple problem of linearly separating a set of points in the Cartesian plane, as depicted in Fig. 1.1

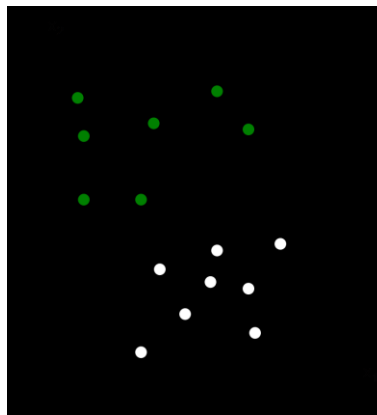


Fig. 1.1 A set of points linearly separable

The question here is how can we classify these points using a linear discriminant function in order to minimize the error rate? We have an infinite number of answers, as shown in Fig. 1.2:

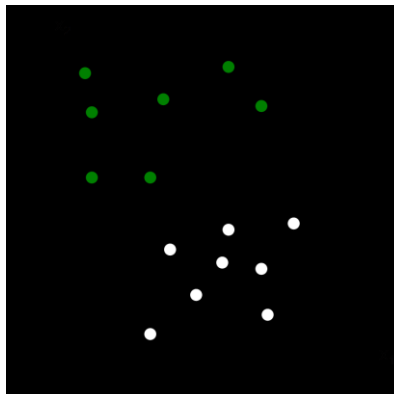


Fig. 1.2 Linear classifiers that can discriminate between the set of points

From the multitude of solutions we need to find out which is the best one. The answer is given by the linear discriminant function (classifier) with the maximum margin is the best. Margin is defined as the width that the boundary could be increased by before hitting a data point, Fig. 1.3.

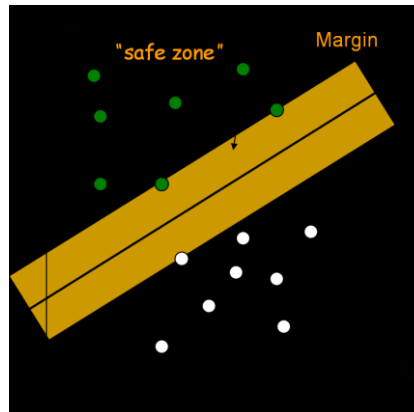


Fig. 1.3 The margin of a linear classifier

This classifier is the best because it is robust to outliers and thus has strong generalization ability.

Given a set of data points: $\{x_i, y_i\}, i = 1, 2, \dots, n$ where

$$\text{For } y_i = +1, w^T x_i + b > 0$$

$$\text{For } y_i = -1, w^T x_i + b < 0$$

With a scale transformation on both w and b , the above is equivalent to:

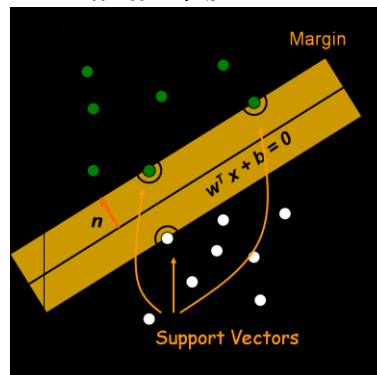
$$\text{For } y_i = +1, w^T x_i + b \geq 1$$

$$\text{For } y_i = -1, w^T x_i + b \leq -1$$

We know that:

$$w^T x^+ + b = 1$$

$$w^T x^- + b = -1$$



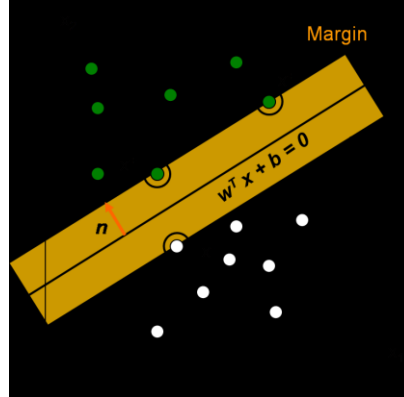
The margin width is:

$$M = (x^+ - x^-) \cdot n = (x^+ - x^-) \cdot \frac{w}{\|w\|} = \frac{2}{\|w\|}$$

This margin should be maximized. The maximization problem is difficult to solve because it depends on $\|w\|$, the norm of w , which involves a square root. Fortunately it is possible to alter the equation by substituting $\|w\|$ with $\frac{1}{2}\|w\|^2$ without changing the solution (the minimum of the original and the modified equation have the same w and b).

This is a quadratic programming (QP) optimization problem. More clearly we need to:

- minimize $\frac{1}{2} \|w\|^2$ such that:
- For $y_i = +1, w^T x_i + b \geq 1$
- For $y_i = -1, w^T x_i + b \leq -1$



Which is equivalent to minimize $\frac{1}{2} \|w\|^2$ such that $y_i(w^T x_i + b) \geq 1$.

The solution to this optimization problem is found by Lagrangian multipliers, but it is not the purpose of this lab.

2.2. Soft-margin classifiers

In 1995, Corinna Cortes and Vladimir Vapnik suggested a modified maximum margin idea that allows for mislabeled examples. If there exists no hyperplane that can split the "yes" and "no" examples, the Soft Margin method will choose a hyperplane that splits the examples as cleanly as possible, while still maximizing the distance to the nearest cleanly split examples. The method introduces slack variables, ζ_i , which measure the degree of misclassification of the datum x_i .

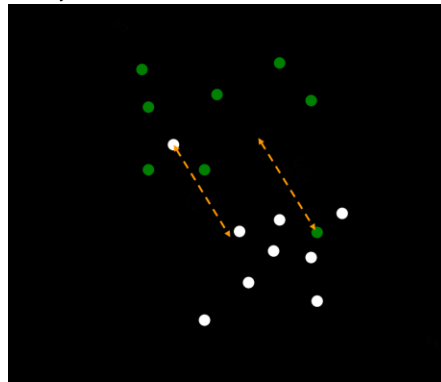


Fig. 1.4 Classification using soft margin

By minimizing $\sum_i \zeta_i$, we can obtain ζ_i by:

$$\begin{cases} w^T x_i + b \geq 1 - \zeta_i & y_i = 1 \\ w^T x_i + b \leq -1 + \zeta_i & y_i = -1 \\ \zeta_i \geq 0 & \forall i \end{cases}$$

- ζ_i are "slack variables" in optimization;
- $\zeta_i = 0$ if there is no error for x_i , and
- ζ_i is an upper bound of the number of errors

So we have to minimize $\frac{1}{2} \|w\|^2 + C \sum_{i=1}^n \xi_i$ such that $y_i(w^T x_i + b) \geq 1 - \xi_i$ and $\xi_i \geq 0$. Parameter C can be viewed as a tradeoff parameter between error and margin.

2.3. Support vector machine with soft margin classification

Remember from the previous lab that if the data is non-linearly separable a transformation is applied to each sample x_i such that $x_i \rightarrow \phi(x_i)$.

Given a training set of instance-label pairs (x_i, y_i) ; $i = 1 \dots l$ where $x_i \in R^n$ and $y_i \in \{+1, -1\}$, the support vector machines (SVM) require the solution of the following optimization problem:

$$\min_{w, b, \xi} \quad \frac{1}{2} w^T w + C \sum_{i=1}^l \xi_i$$

Subject to:

$$y_i(w^T \phi(x_i) + b) \geq 1 - \xi_i,$$

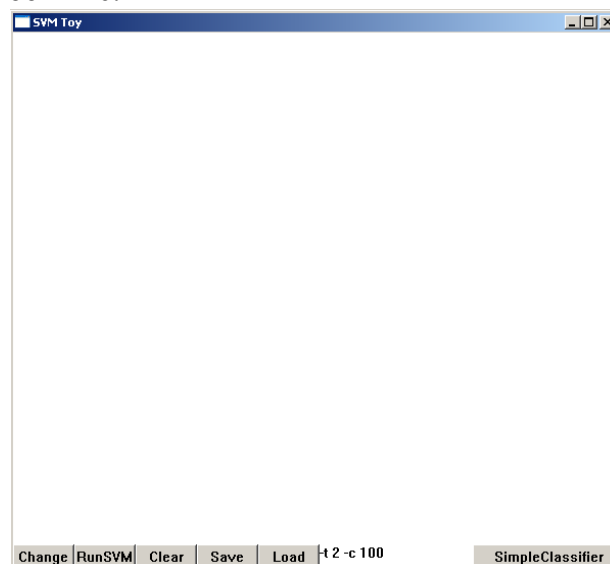
$$\xi_i \geq 0.$$

Here training vectors x_i are mapped into a higher (maybe infinite) dimensional space by the function Φ . Then SVM finds a linear separating hyperplane with the maximal margin in this higher dimensional space. $C > 0$ is the penalty parameter of the error term. Furthermore, $K(x_i, x_j) = \Phi(x_i)^T \Phi(x_j)$ is called the kernel function. Though new kernels are being proposed by researchers, beginners may find in SVM books the following four basic kernels (linear, polynomial, radial basis function, sigmoid – see the previous lab!).

3. Exercises

For the practical work you will be given a framework called *SVM-toy*, that provides a C++ implementation of soft-margin classifiers using different types of kernels.

1. Download *TestSVM.zip*. Compile *SVM-toy* and run it (on VisualStudio2005). Its interface should look like:



The buttons of the interface have the following meaning:

- ‘Change’ button: the application allows the user to add points in the classification space (the white window) by mouse left click; this button allows to change the color of the points (each color corresponds to a class). A maximum number of three colors is allowed (hence three classes)
- ‘RunSVM’ button – runs the SVM classifier with the parameters specified in the edit box
- ‘Clear’ button – clears the classification space
- ‘Save’ button – saves the points (normalized coordinates) from the classification space to a file
- ‘Load’ button – loads a bitmap image (loads and draws the points into the classification space)
- The Edit box where parameters are specified, the default values are ‘-t 2 -c 100’

The application allows several parameters, but we will use two of them, naming:

- ‘-t kernel_type’ specifies the kernel type: set type of kernel function (default 2); ‘kernel_type’ can be one of the following:
 - 0 – linear kernel: $u \cdot v$
 - 1 – polynomial kernel: $(\gamma u \cdot v + \text{coef0})^{\text{degree}}$
 - 2 – radial basis function: $\exp(-\gamma |u-v|^2)$
 - 3 – sigmoid: $\tanh(\gamma u \cdot v + \text{coef0})$
 - ‘-c cost’ specifies the parameter C from the soft margin classification problem
 - ‘SimpleClassifier’ button – implements the simple classifier (to do! - see the previous lab).
2. For each image in *svm_images.zip* run the default SVM classifier (with different kernels and costs)
 3. Implement the ‘SimpleClassifier’ code and compare it to the SVM classifier that uses a linear kernel.

Write the code in the file *svm-toy.cpp* for the case branch:

```
case ID_BUTTON_SIMPLE_CLASSIFIER:
{
/* *****
    TO DO:
    WRITE YOUR CODE HERE FOR THE SIMPLE CLASSIFIER
***** */
}
```

For implementing the simple classifier (from the previous lab) you should know that in the *svm_toy.cpp* file the coordinates of the points are stored in the structure

```
list<point> point_list;
```

and a point is defined by the structure:

```

struct point {
    double x, y;
    signed char value;
};

```

The variable 'value' represents the class label.

The coordinates of the points are normalized between 0 and 1 and the (0,0) point is located in the top left corner.

Notice that the dimension of the classification space is XLEN x YLEN. Hence to a normalized point (x,y) we have other coordinates in the classification space (drawing space) which are (x*XLEN, y*YLEN).

The drawing of a segment between two points is done by the method:

```

DrawLine(window_dc, x1, y1, x2, y2, RGB(255,0,0));

```

In order to iterate over all the points and count how many points are in class '1' and in class '2' you should do the following:

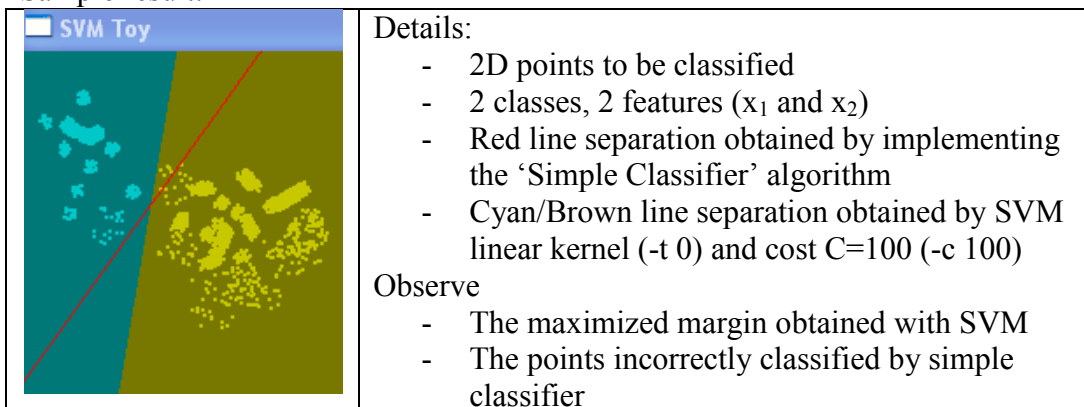
```

//declare an iterator
list<point>::iterator p;
int nrSamples1=0;
int nrSamples2=0;
double xC1=0, xC2=0, yC1=0, yC2=0;

for(p = point_list.begin(); p != point_list.end(); p++)
{
    if ((*p).value==1) //point from class '1'
    {
        nrSamples1++;
        xC1 = (*p).x; //normalized x coordinate of the current point
        yC1 = (*p).y; //normalized y coordinate of the current point
    }
    if ((*p).value==2) //point from class '2'
    {
        nrSamples2++;
        xC2 = (*p).x; //normalized x coordinate of the current point
        yC2 = (*p).y; //normalized y coordinate of the current point
    }
}

```

Sample result:



4. References

[1] Jinwei Gu - *An Introduction to SVM*:

<http://www1.cs.columbia.edu/~belhumeur/courses/biometrics/2009/svm.ppt>

[2] J. Shawe-Taylor, N. Cristianini: *Kernel Methods for Pattern Analysis*. Pattern Analysis (Chapter 1)

[3] B. Scholkopf, A. Smola: *Learning with Kernels*. A Tutorial Introduction (Chapter 1), MIT University Press.

[4] LIBSVM: <http://www.csie.ntu.edu.tw/~cjlin/libsvm/>