

Interrupt-Driven I/O

- Principle of Interrupt-Driven I/O
- Multiple-Interrupt Systems
- **Priority Interrupt Systems**
 - Parallel Priority Interrupts
 - Daisy-Chain Priority Interrupts

Priority Interrupt Systems (1)

- In case of simultaneous requests, a **priority system** is needed
- Establishing the priority of simultaneous interrupts can be done in **software** or in **hardware**
- **Software method:**
 - Identification of the highest-priority source is made by **polling**
 - There is a **common service routine**, which polls the interrupt sources

Priority Interrupt Systems (2)

- The order in which the sources are polled determines their priority
- **Disadvantage:** if there are many sources, the time required for polling increases
- **Hardware method:**
 - An interrupt controller accepts interrupt requests from many sources and **determines the highest priority request**
 - Each source has **its own interrupt vector**

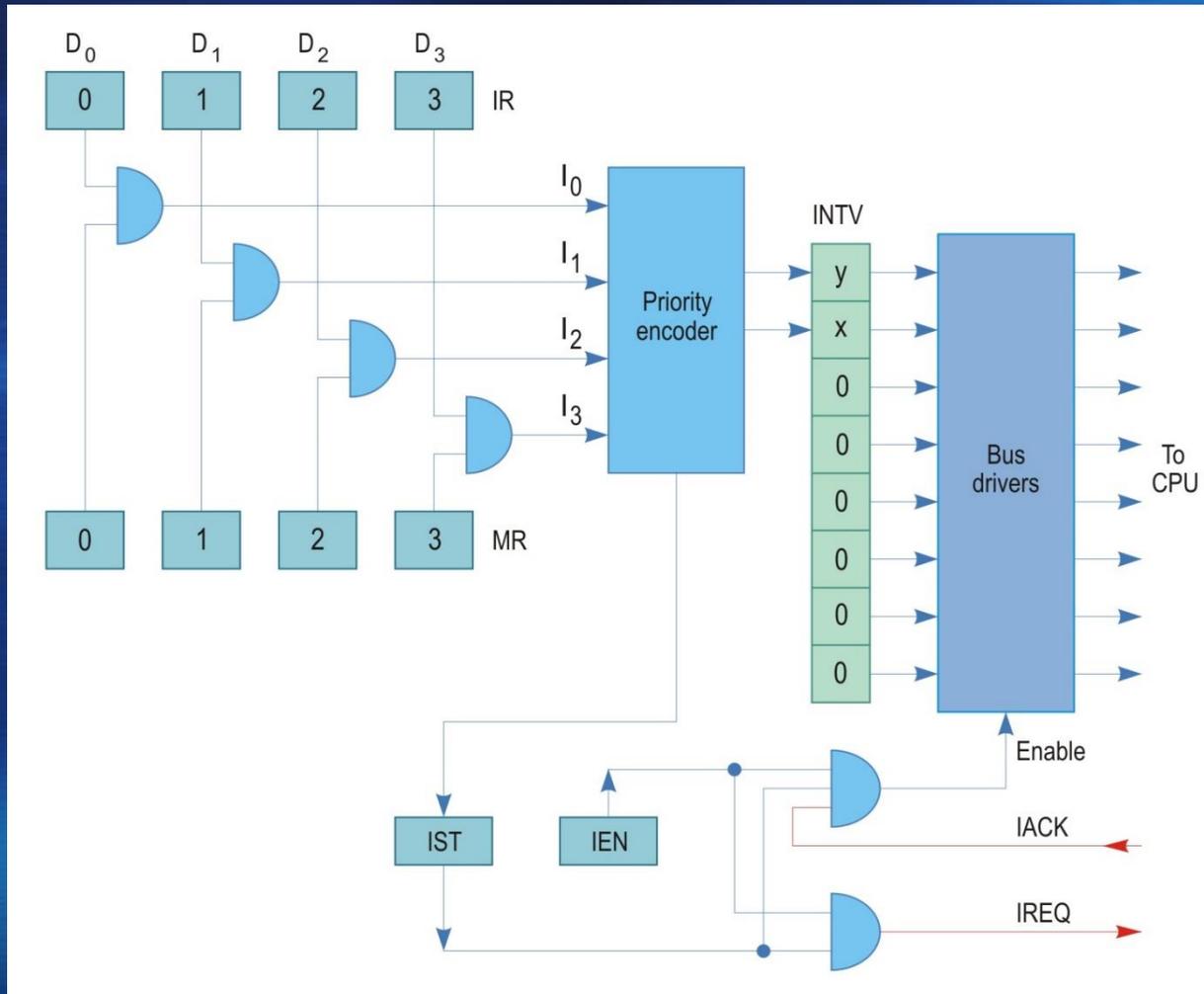
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Parallel Priority Interrupts (1)

- An interrupt request register IR is used
 - Its bits are set separately by the interrupt requests of each device
- Priority is established according to the position of bits in the register
- The interrupt mask register MR allows to control (disable) the status of each interrupt request

Parallel Priority Interrupts (2)



Parallel Priority Interrupts (3)

- The priority encoder:
 - Implements the priority function
 - Generates two bits of the interrupt vector
- The vector is transferred to the CPU via tristate buffers
- Enabling the buffers: with the *IACK* signal from the CPU, and the *IST*, *IEN* flags
 - *IST* – interrupt status flag
 - *IEN* – interrupt enable flag

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Daisy-Chain Priority Interrupts (1)

- All devices that can generate an interrupt request are connected in a daisy-chain
 - Each device has a **PI** (*Priority In*) input and a **PO** (*Priority Out*) output
 - The device with the **highest priority** is placed in the **first position**
- The interrupt request line is shared by all devices (**wired OR** connection)

2. Methods for I/O Operations

- Programmed I/O
- Interrupt-Driven I/O
- Direct Memory Access (DMA)
- I/O Processors

Direct Memory Access (DMA)

- Principle of I/O through DMA
- Execution of DMA Transfers
- Configurations of Systems Using DMA Transfers

Principle of I/O through DMA (1)

- **Disadvantage** of programmed I/O and interrupt-driven I/O: the CPU is busy with managing the I/O operations
- DMA eliminates this disadvantage → data transfers are executed directly between the internal memory and the I/O system
- An additional module is required → **DMA controller**
- **Two methods for performing transfers through DMA** →

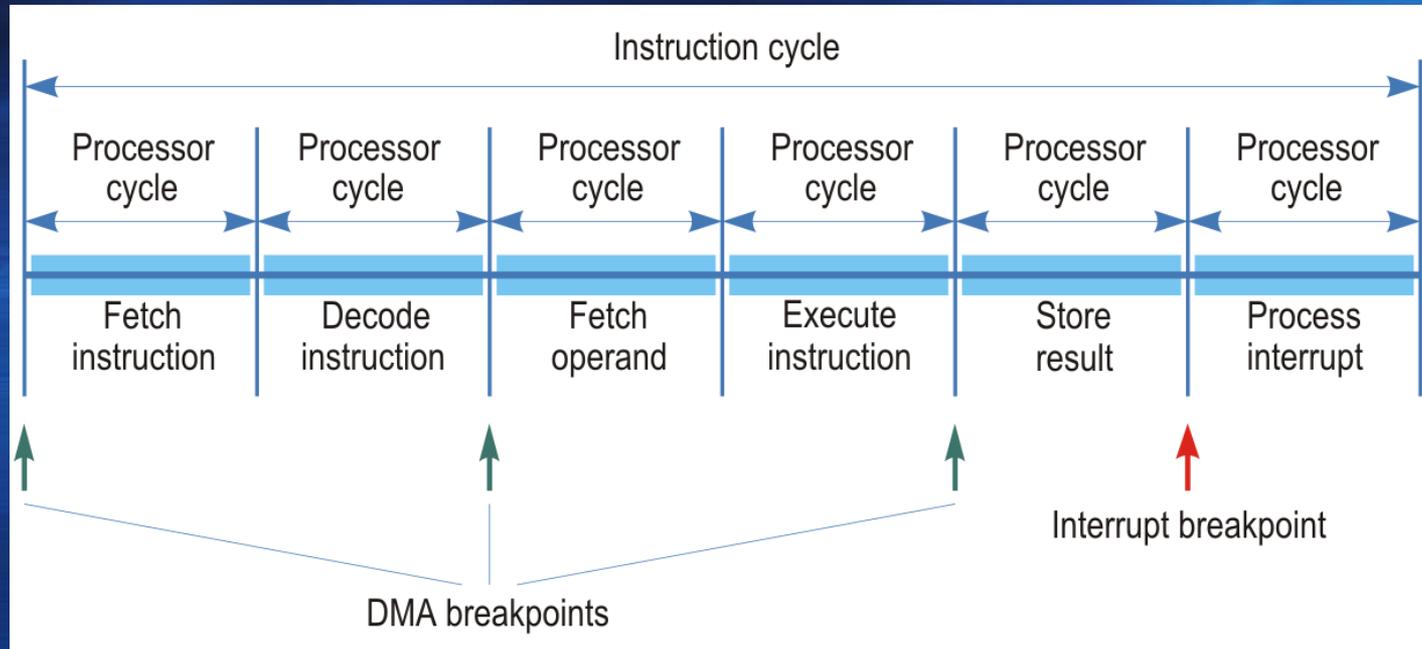
Principle of I/O through DMA (2)

1. By suspending the CPU operations and placing the bus in the high-impedance state during the transfer
 - Data break or block transfer
 - This method is required, e.g., for magnetic disk drives → data transmission cannot be stopped or slowed down
 - The CPU is inactive for relatively long time periods

Principle of I/O through DMA (3)

2. By using the time intervals when the CPU does not access the memory
 - Cycle stealing
 - Large blocks of data are transferred by a sequence of DMA bus transactions interspersed with CPU bus transactions
 - The method **reduces the maximum transfer rate**, but it also reduces the interference of the DMA controller in accessing memory by the CPU

Principle of I/O through DMA (4)



Breakpoints of the CPU for performing transfers through DMA and through interrupts

Direct Memory Access (DMA)

- Principle of I/O through DMA
- Execution of DMA Transfers
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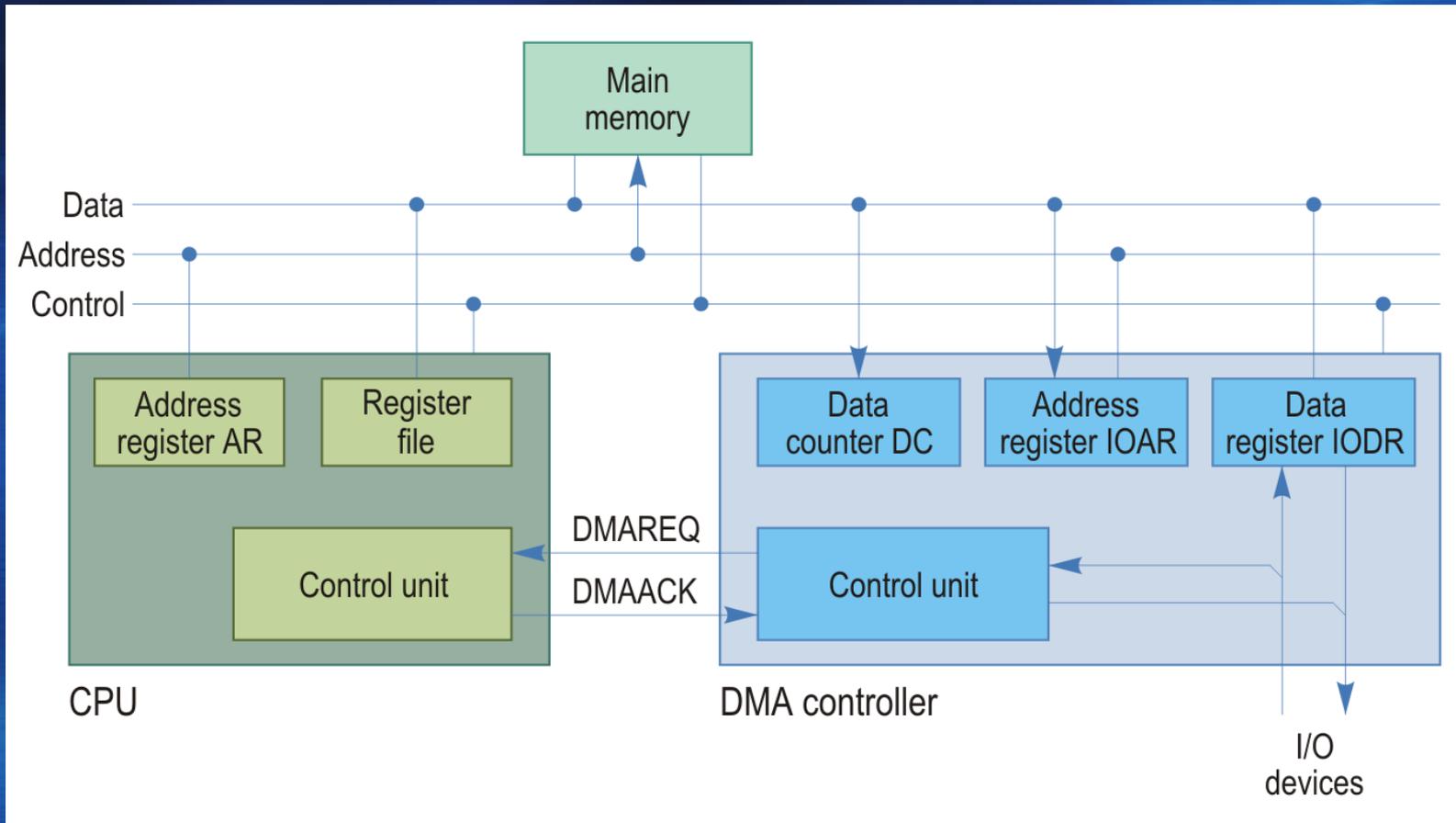
Execution of DMA Transfers (1)

- The CPU sends an initialization sequence to the DMA controller
- The initialization sequence contains:
 - Direction of transfer (read or write)
 - Address of the I/O device involved
 - Starting address of the memory area used for the transfer
 - Number of bytes or words to be transferred

Execution of DMA Transfers (2)

- The CPU releases the bus and may execute other operations
- The DMA controller generates the addresses and control signals needed for the transfer
- After a DMA cycle, other cycles may follow, or the control is transferred to the CPU
- When the transfer is complete, the DMA controller generates an interrupt request to the CPU

Execution of DMA Transfers (3)



Execution of DMA Transfers (4)

1. The CPU loads the **IOAR** and **DC** registers with initial values → I/O instructions
2. When the DMA controller is ready for the transfer, it asserts the **DMAREQ** signal
 - At the next DMA breakpoint, the CPU releases the bus and asserts **DMAACK**
3. The DMA controller transfers data directly with the main memory; the **IOAR** and **DC** registers are updated

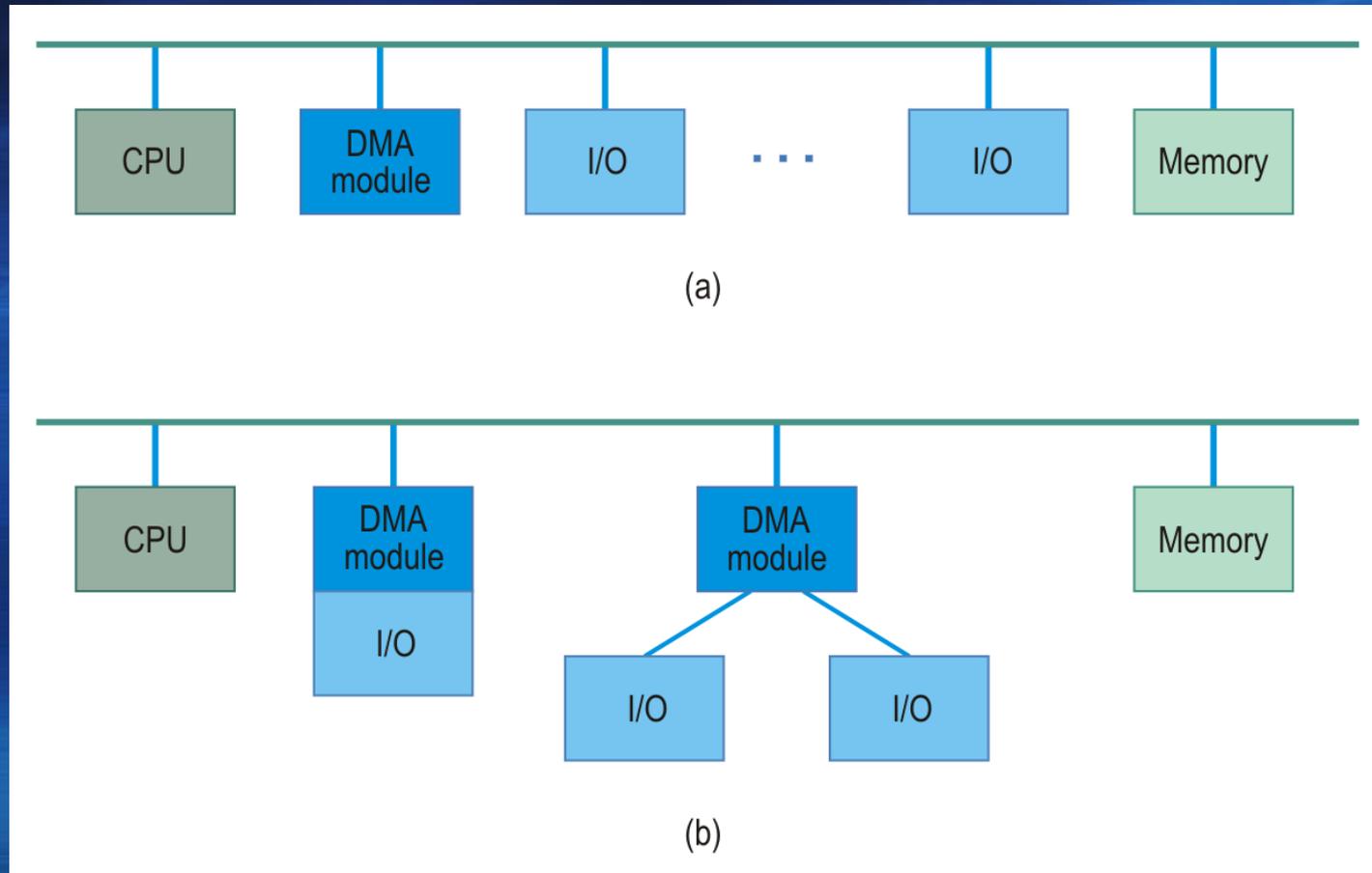
Execution of DMA Transfers (5)

4. If the **DC** register $\neq 0$, but the I/O device is not ready, the DMA controller releases the bus
 - The CPU disables the **DMAACK** signal and takes control of the bus
5. If the **DC** register = 0, the DMA controller releases the bus and sends an interrupt request to the CPU
 - The CPU responds by halting the I/O device or by initiating a new transfer

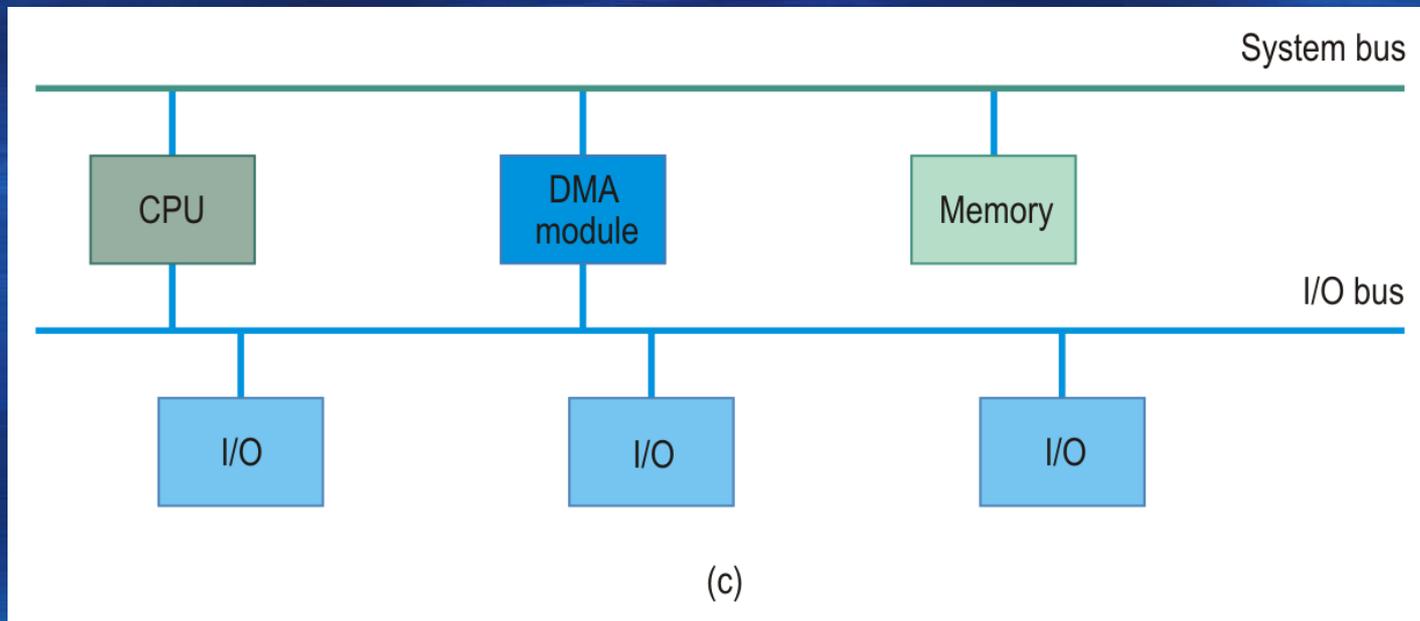
Direct Memory Access (DMA)

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Configurations of Systems Using DMA Transfers (1)



Configurations of Systems Using DMA Transfers (2)



2. Methods for I/O Operations

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I/O Processors

- Principle of I/O through I/O Processors
- Execution of an I/O Program

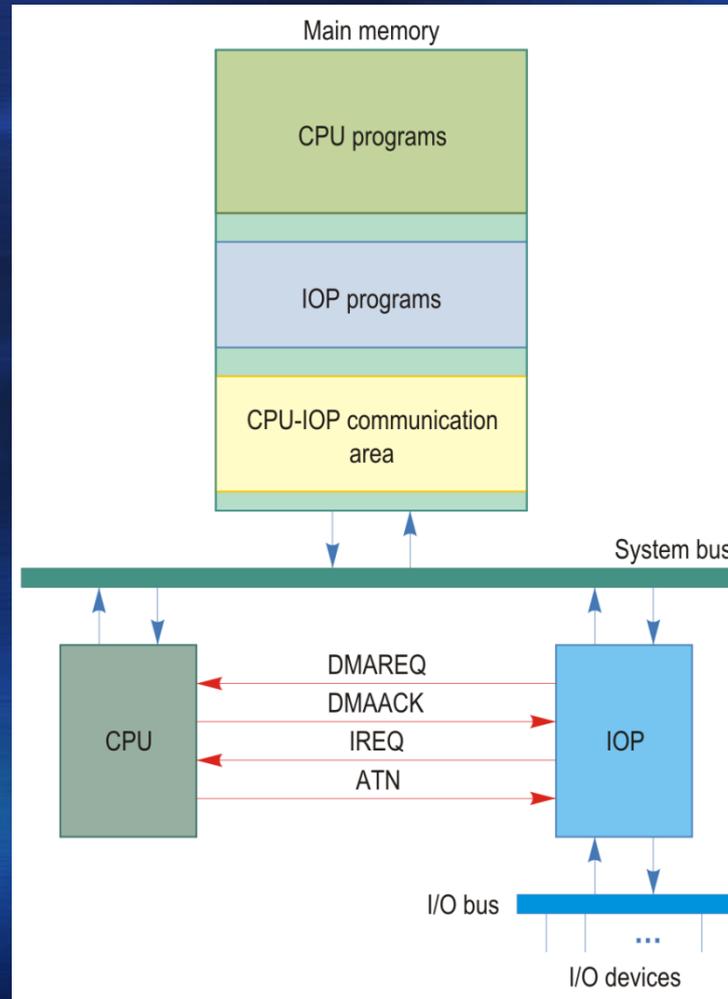
Principle of I/O through I/O Processors (1)

- While DMA releases the CPU from many I/O operations, for high-speed peripherals numerous bus cycles will be needed
 - During these cycles, the CPU enters a wait state
 - The cycle stealing will saturate the bus
 - A certain time is required to service the interrupts
- The I/O modules have been improved, becoming *I/O processors* (IOPs)

Principle of I/O through I/O Processors (2)

- Some of these I/O modules are also called *I/O channels*
- IOPs have a **specialized instruction set** for I/O operations
- The CPU sends a command to the IOP to execute an *I/O program (channel program)* located in memory
- The CPU can specify a sequence of I/O operations, and is interrupted only at the completion of the entire sequence

Principle of I/O through I/O Processors (3)



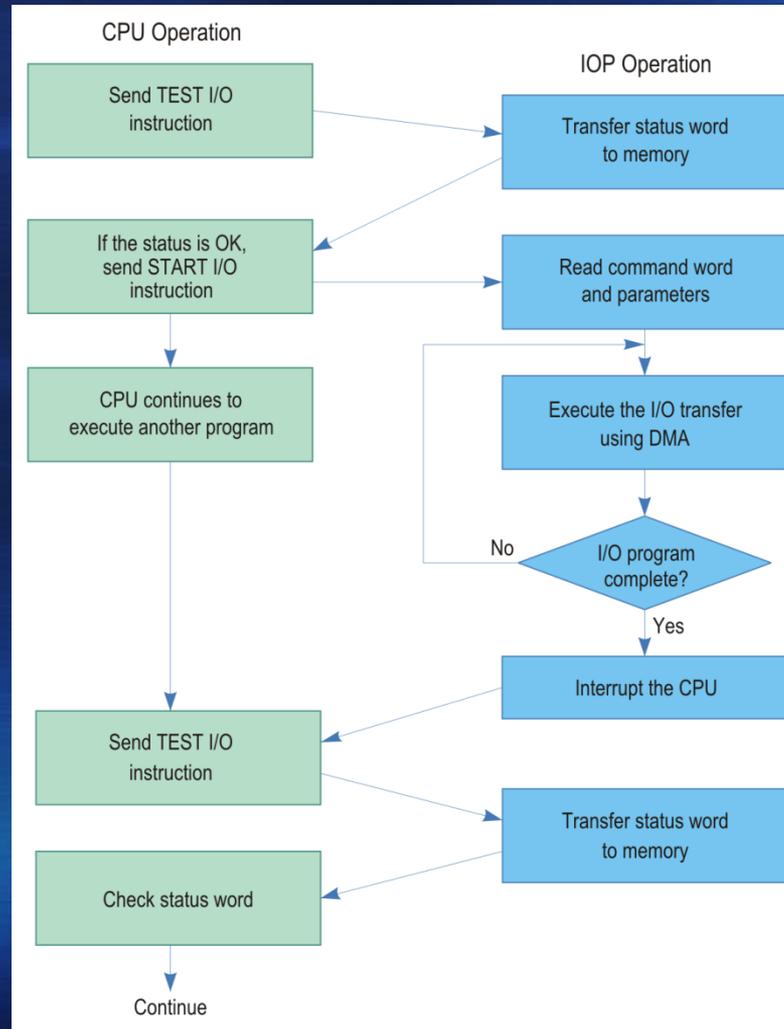
Principle of I/O through I/O Processors (4)

- The CPU and IOP can also communicate with each other directly via control lines
 - DMA Request (*DMAREQ*)
 - DMA Acknowledge (*DMAACK*)
 - The CPU may attention the IOP by asserting the *ATN* (*Attention*) signal → execution of an I/O program
 - The IOP may attention the CPU by asserting the *IREQ* signal → execution of an interrupt service routine

I/O Processors

- Principle of I/O through I/O Processors
- Execution of an I/O Program

Execution of an I/O Program



Summary (1)

- Establishing the priority of interrupts can be done with two methods:
 - **Software method**: polling in a common interrupt handler
 - **Hardware method**: using an interrupt controller
- The **DMA technique** allows performing I/O transfers without CPU intervention
 - Two methods for performing DMA transfers: **data break** (block transfer) or **cycle stealing**

Summary (2)

- An **I/O processor** (IOP) has specialized instructions for I/O operations
 - Can execute a sequence of I/O operations without interrupting the CPU
 - The CPU and an IOP communicate via a **memory area** and via **control signals**

Concepts, Knowledge (1)

- Software polling technique
- Hardware polling technique
- Methods for establishing the priority of simultaneous interrupts: software method; hardware method
- Parallel connection of interrupt lines
- Daisy-chain connection of interrupt lines
- Principle of I/O through DMA

Concepts, Knowledge (2)

- Data-break DMA transfer method
- Cycle-stealing DMA transfer method
- Execution of DMA transfers
- Diagram of circuitry required for DMA transfers
- Principle of I/O through IOP
- Structure of a computer with IOP
- CPU-IOP communication
- Operations for execution of an I/O program