

# Computer Programming

## Functions. Arrays

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Course 4



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# Functions - introduction

- a function is a self-contained unit of a program that receives input data through parameters, performs calculations, and returns results
- it is a miniature program
- it is good practice to write functions without secondary effects = changes to external variables
- they should also be deterministic = produce the same results for the same input
- enforcing these recommendations leads to functional programming
- the proper application of functions ensures code reusability, abstraction, and readability



# Function declaration

- similarly to variables, all functions must be declared
- the declaration specifies, in this order:
  - return type, function name, list of input parameters with their types
- the declaration of a function is called its **header** or **prototype**
- the declaration can be followed by a semicolon
  - it just defines the function interface and no functionality
- or it can be followed by the function definition
  - specifying the exact operations the function should perform



# Function declaration - syntax

`type function_name(type1 in_param1, type2 in_param2, ...)`

- similar to how we use functions in mathematics:  $y = f(x)$
- the type of the value which is returned from the function is specified first
- it is followed the name of the function
- the formal input parameters are given next inside parentheses



# Function declaration - return type

- functions may return any primitive C type
- pointers and structures can also be returned (more details later)
- if no value is returned, the return type should be set to *void*
  - example: printing only
- any value that is returned from the function using the **return** statement is *converted implicitly* to the return type of the function
- should be specified, if not given, *int* is assumed



# Function declaration - name

- the function name should adhere to the same rules as the ones required for naming variables (do not start with numbers, single word, case sensitive)
- multiple words can be linked with underscore or camelCase
- should be suggestive but not long
- it is recommended to construct it using a verb and an object in order to describe an action (`print_digits`, `convert_binary`)



# Function declaration - formal parameters

- **parameters** specify the format of the input data
- it is a list of types and names (names are optional)
- syntax is similar to variable declaration
  - however, all types should be given explicitly (cannot be grouped)
  - correct: `f(int a, int b);`
  - also correct: `f(int, int);` - only types are required
  - incorrect: `f(int a, b)` - compilation error
- they are called formal parameters because they only describe the data type and do not hold actual data



# Function definition

- it can be done right after function declaration (most common)
  - in this case, the statements comprising the function body are given right after the header inside curly brackets `{}`
- it can be done later (even in a different source file)
  - in this case the declaration ends with a semicolon and the function definition repeats the function header with names for the formal input parameters
- the `return` statement inside a function ends its execution
- for non-void functions
  - `return` also sends a result value to the function caller
  - all execution branches should have `return` statements, and preferably they should be placed at the end
- for void functions:
  - `return` statement is optional
  - the function execution ends after the last statement



# Function call

- once a function is declared it can be used
- using a function for its result or its secondary effects is termed **calling the function**
- this is achieved by writing the function name and giving it the required input arguments
- the **arguments** are the actual values sent to the function = actual parameters
- the function call can be used in an expression and will be evaluated during run-time
- during program execution, the function definition must be available



## Program 4.1 - simple example

```
1 #include <stdio.h>
2 int last_bit(int x){
3     if (x&1)
4         return 1;
5     else
6         return 0;
7 }
8
9 int main(){
10     int b = last_bit(5);
11     printf("%d\n", b);
12     int x = 1024;
13     printf("%d\n", last_bit(x));
14     return 0;
15 }
```

- the function is declared and defined right after
- it returns an int value and accepts as input parameter an int value
- both branches have a return statement
- function call with a literal (constant number)
- function call with a variable as argument
- calls can be used as expressions



## Program 4.2 - advanced example

```
1 #include <stdio.h>
2 void reverse_binary(int);
3
4 int main(){
5     reverse_binary(123);
6     return 0;
7 }
8
9 void reverse_binary(int x){
10     while(x){
11         printf("%d", x&1);
12         x >>= 1;
13     }
14     return;
15     puts("after return");
16 }
```

- the function is declared before *main*
- *void* return type, used for printing
- expects a single int value
- function call, no return value to be saved
- function definition happens later
- return statement ends the function, nothing after it will be executed



# Passing by value

- function arguments are always **passed by value** in C
- this means only the contents of variables are passed
- perhaps a more descriptive term would be: passing after copying
- if variables are sent to the function, their values will not change
- the function acts as an independent program with its own variables that do not affect the outside world
- it is possible to obtain a different behavior using another mechanism



## Program 4.3 - incorrect interchange

```
1 #include <stdio.h>
2 void interchange(int a, int b){
3     int t = a;
4     a = b;
5     b = t;
6     printf("in func a = %d, b = %d\n",
7           a, b);
8 }
9
10 int main(){
11     int a = 1, b = 2;
12     printf("before a = %d, b = %d\n",
13           a, b);
14     interchange(a, b);
15     printf("after a = %d, b = %d\n",
16           a, b);
17     return 0;
18 }
```

- the input arguments are sent by value
- *a* and *b* inside the function are different variables from the ones from *main*
- they just hold the values of *a* and *b* initially
- no changes occur in the context of the main function



## Example functions from the library

`int rand();` from `stdlib.h`

- returns a pseudo-random integer between 0 and `RAND_MAX`

`double pow(double base, double exponent);` from `math.h`

- returns  $base^{exponent}$
- works with floating point types = imprecise

`float atan2f(float y, float x);` from `math.h`

- returns the arctangent (angle) of the fraction  $\frac{y}{x}$  in the correct quadrant, in radians  $\in [-\pi, \pi]$
- always consult the documentation when employing functions from the library



## Program 4.4 - incorrect pow

```
1 #include <stdio.h>
2 #include <math.h>
3
4 int main(){
5     long long x = pow(10, 18) - 100;
6     printf("%lld\n", x);
7     return 0;
8 }
```

- the pow function works with floating point numbers
- if exact values are required this should be avoided
- the integer arguments 10 and 18 are converted to double
- the result is a double with 15 digit precision = last 3 digits may be wrong
- conversion to long long happens only after calculations are done



# Call stack

- it is a memory zone for storing local variables, function arguments, and function return addresses
- it is a stack because values are put on the top of stack, and they are also extracted from the top
- this policy is called Last In First Out (LIFO)
- the size of the stack by default is of the order of MBs
- programmers must not exceed the stack limit
  - use local variables of reduced dimensions
  - limit the number of recursive function calls
- stack limit can be changed, but this is not recommended



## Program 4.5 - stack overflow

```
1 int f(int n){
2     if (n == 0)
3         return 0; //C
4     return n + f(n-1); //B
5 }
6
7 int main(){
8     int n = 1e6;
9     f(n); //A
10    return 0;
11 }
```

- recursive function = it calls itself
- line C: halting condition
- line B: line where control should return to after function execution
- line A: source of recursive function calls
- the double literal 1e6 is in scientific notation
- it is equal to  $10^6$ , conversion to int happens implicitly



# Stack snapshot

The stack when the halting condition is reached starting from  $n = 3$ :

$f$	$n = 0$	line C
$f$	$n = 1$	line B
$f$	$n = 2$	line B
$f$	$n = 3$	line B
main	$n = 3$	line A

- there are multiple instances of the  $f$  function on the call stack
- the most recent call is on top
- the calls further down depend on and wait for the result from the upper calls
- each call has its own value for  $n$  and the line where it should return to after the call ends



# Study problem - Greatest Common Divisor

- you are given two integers  $a, b \leq 10^9$
- determine their greatest common divisor
- solve the special cases:
  - $a$  and  $b$  can be 0
  - common when working with fractions
  - in fact, the method we will derive works on negative numbers and on even larger numbers
- we will look at Euclid's algorithm
- it is efficient, compact, elegant and handles all special cases



## Study problem - Greatest Common Divisor

We will exploit the following property to propose an algorithm:

### Lemma

*If  $a$  is a multiple of  $d$  and  $b$  is a multiple of  $d$ , then  $a-b$  is a multiple of  $d$ .*

```
while  $a \neq b$  do  
  if  $a > b$  then  
     $a = a - b$   
  else  
     $b = b - a$   
  end if  
end while  
 $d = a$ 
```



# Study problem - Greatest Common Divisor

There are two main issues with the previous approach:

- it is slow if  $a$  is large and  $b$  is relatively small
- it does not work if the smaller number is 0

If the smaller number is positive the algorithm halts.

- this is because at each step, the larger number is decreased by at least 1
- at every step both  $a$  and  $b$  are divisible by their gcd
- in the worst case,  $\text{gcd} = 1$ ,  $a$  and  $b$  are reduced until they both become 1



## Study problem - Greatest Common Divisor

Recall a relevant theorem for calculating the remainder after division:

### Theorem

*If  $a$  is an integer and  $d$  is natural number, then there exist unique integers  $q$  and  $r$ ,  $0 \leq r < d$  such that:*

$$a = qd + r$$

If  $g$  is the greatest common divisor of  $a$  and  $b$ , then  $g$  also divides the remainder  $r$  of  $a$  divided by  $b = a \% b$ .

This is because if  $g$  divides both  $a$  and  $b$ , then it divides  $a - b$ ,  $a - 2b$ , ...,  $a - qb = r$ , by applying the Lemma multiple times, until we obtain a number  $r$  less than  $b$ .



# Code snippet - Greatest Common Divisor

```
1 int gcd(int a, int b){  
2     while(b){  
3         int r = a%b;  
4         a = b;  
5         b = r;  
6     }  
7     return a;  
8 }
```

- if  $b$  is zero the answer is  $a$
- if  $a < b$ , then  $a$  and  $b$  are swapped
- otherwise, find the remainder  $r$
- the  $gcd$  divides this remainder
- continue with  $(b, r)$  instead of  $(a, b)$
- number of steps is approximately  $\log_{\varphi}(a + b)$ , with  $\varphi = \frac{1+\sqrt{5}}{2}$



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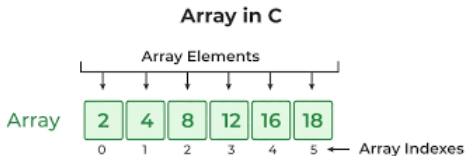
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# Arrays - Introduction

- an array consists of multiple variables which occupy a contiguous memory location
- sequences appear naturally in problems
- for example, the first  $n$  even numbers
- allows programmatic access to a specific element = the position can be calculated





# Array declaration

- arrays are declared by specifying the type, the name and the number of elements in square brackets  
`element_type array_name[nr_elements];`
- the type of each element can be any primitive C type or more advanced
- the number of elements can be a variable, but it will be fixed at the moment of declaration
- multidimensional arrays can be declared by giving the number of elements for each dimension

```
1 int a[5];  
2 int n = 4;  
3 int matrix[n][n];
```



## Element access

- an array with  $n$  elements reserves space for  $n$  variables of the specified type
- these will occupy a contiguous memory zone (without breaks)
- an element from the array can be accessed for both reading and writing by:

`array_name[element_pos]`

- arrays use 0-indexing for a good reason
  - the first element is located at position 0
  - the last element is located at position  $n-1$
- Caution!
  - the  $n$ -th position is not part of the array
  - accessing the  $n$ -th position is a mistake and can lead to run-time error (undeterministic behavior)



# Array initialization

- arrays can be initialized right at their declaration using a syntax with braces `{}`
- elements are enumerated, starting from the first (0th)
- without initialization, the elements of the array are random values
- if an array is initialized with values, its dimension can be deduced automatically and it can be omitted from the declaration
- if the size of the array is specified and initialization is also done, the unspecified elements are initialized with 0

```
1 int a[5] = {1, 2, 0};  
2 // a[0] = 1, a[1] = 2, a[2] = a[3] = a[4] = 0  
3 double b[] = {1.2, -0.5};  
4 // the number of elements is deduced to be 2
```



## Array initialization - advanced

- elements from specific positions can be initialized with the [] syntax
- this is especially useful for sparse arrays
- just provide values for specific positions:

```
int a[15] = {[2] = 29, [9] = 7, [14] = 28};
```

- in any order:

```
int a[15] = {[14] = 28, [2] = 29, [9] = 7};
```

- can be mixed with classical initialization:

```
int a[15] = {0, 1, 2, [4] = 4, [3] = 3};
```

- if the dimension of the array is given, all unspecified positions are filled with 0

```
int I[] [] = {[0][0] = 1, [1][1] = 1};
```



# Arrays as function parameters

- arrays can be used as input parameters to functions
- in the following, `name` refers to the name of the array
- for one-dimensional arrays
  - in the function prototype: `type name[]` or `type name[dim]`
  - in function call: `name`
  - if the dimension is a variable, it must be sent before the array
- for multi-dimensional arrays
  - in the function prototype: `type name[][dim2]`
  - the first dimension is optional
  - in function call: `name`
  - if the dimensions are variable, they must be sent before the array



## Program 4.6 - Arrays example

```
1 #include <stdio.h>
2
3 int main()
4 {
5     int n;
6     printf("n = ");
7     scanf("%d", &n);
8     int a[n];
9     for(int i=0; i<n; i++){
10         printf("a[%d] = ", i);
11         scanf("%d", &a[i]);
12     }
13     for(int i=0; i<n; i++)
14         a[i] = 2*a[i];
15     for(int i=0; i<n; i++)
16         printf("a[%d] = %d\n", i, a[i]);
17     return 0;
18 }
```

- the number elements should be known before declaring the array
- during reading, array elements are preceded by the & operator
- elements can be read and written
- arrays in C are 0-indexed



# Array dimension

- there is an instruction called `sizeof` for determining the size of any variable or type in bytes
- it can behave as a function, which receives a variable or a type as input
- for arrays it returns the size of the whole array
- to find the number of elements, the array size should be divided by the size of a single element

```
1 int x = 5;
2 printf("%u %u", sizeof(x), sizeof(int));
3 int a[5];
4 printf("%u %u", sizeof(a), sizeof(a)/sizeof(a[0]));
```



## Program 4.7 - 2D arrays example

```
1 #include <stdio.h>
2
3 void read_mat(int n, float a[][n]){
4     for(int i=0; i<n; i++){
5         for(int j=0; j<n; j++){
6             printf("a[%d][%d] = ", i, j);
7             scanf("%f", &a[i][j]);
8         }
9     }
10 }
11
12 void diag(int n, float a[][n], float d[]){
13     printf("%d\n", sizeof(d));
14     for(int i=0; i<n; i++)
15         d[i] = a[i][i];
16
17 }
```

- read\_mat has as input the variable dimension  $n$  and the matrix  $a$
- the first dimension can be omitted when specifying parameters
- sizeof inside a function on an array doesn't work as expected



## Program 4.7 - 2D arrays example - main

```
19 int main(){
20     int n=2;
21     float a[n][n];
22     float d[n];
23     read_mat(n, a);
24     diag(n, a, d);
25     for(int i=0; i<n; i++)
26         printf("%f ", d[i]);
27     return 0;
28 }
```

- array dimension must be known before declaring it
- single or multidimensional arrays are sent to functions just by their names



## Program 4.8 - Stack overflow 2

```
1 int f(int n){  
2     int a[n];  
3 }  
4  
5 int main(){  
6     f(1000000);    //A  
7     return 0;  
8 }
```

- arrays can get very large
- $a$  is declared inside the function  $f$
- the required space is reserved on the stack
- will likely result in run-time error, depending on the size of stack



## Program 4.9 - Interchange

```
1 #include <stdio.h>
2 void interchange(int ab[]){
3     int t = ab[0];
4     ab[0] = ab[1];
5     ab[1] = t;
6     printf("in func a = %d, b = %d\n",
7         ab[0], ab[1]);
8 }
9 int main(){
10     int ab[] = {1, 2};
11     printf("before a = %d, b = %d\n",
12         ab[0], ab[1]);
13     interchange(ab);
14     printf("after a = %d, b = %d\n",
15         ab[0], ab[1]);
16     return 0;
17 }
```

- why does the swap work?